

Magnetic Sensors: An Overview



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Outline

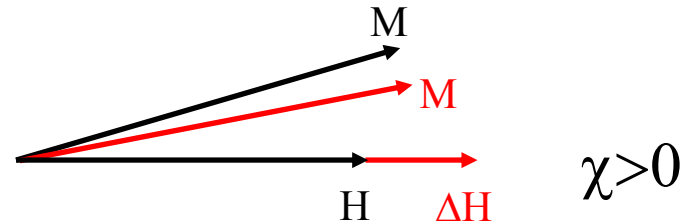
- Part A: Engineering Theory of Magnetism
 - A short introduction to magnetics
 - The magnetization process
 - Magnetic effects for engineering applications
- Part B: Sensors Based on Magnetic Materials
 - Sensing principles based on magnetic effects
 - Applications of sensors based on magnetic materials
 - Developing a sensor

Part A:

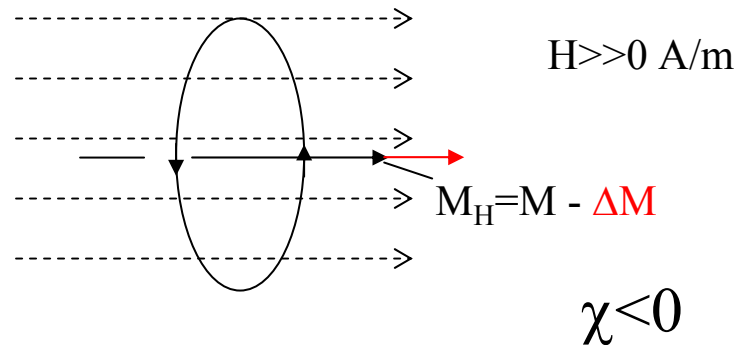
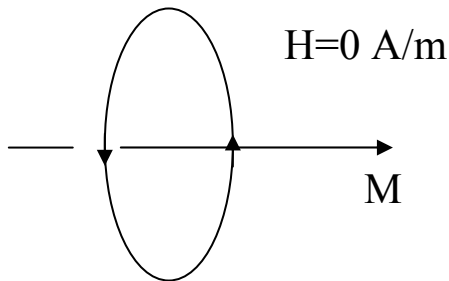
Engineering Theory of Magnetism

A short introduction to magnetics

- Paramagnetism

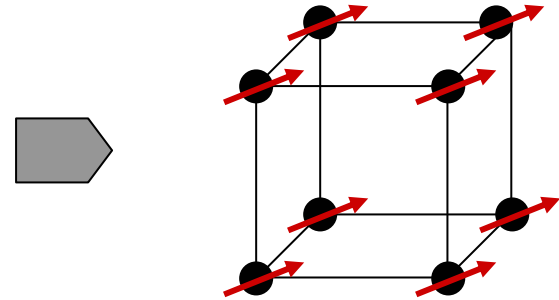


- Diamagnetism

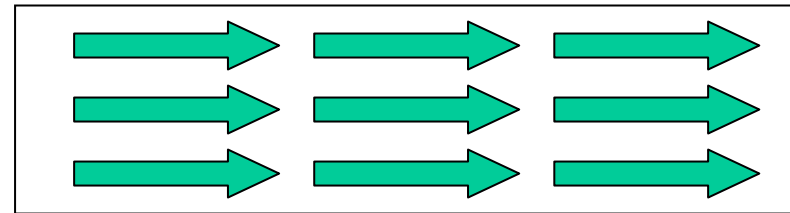


Ferromagnetism

- **Short range or exchange** interaction results in spin-spin alignment of neighboring spins in some TM materials



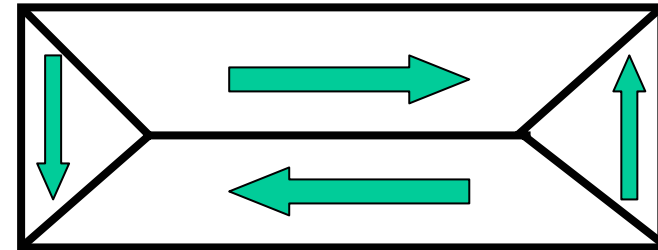
- The spin-spin alignment results in the formation of the so called **ferromagnetic domains**



Ferromagnetism

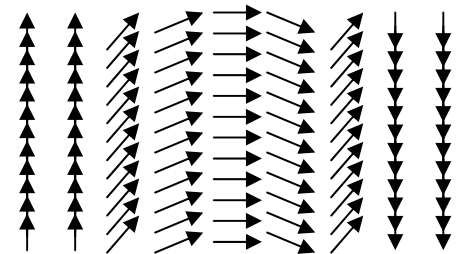
Magnetic domains cannot be extended to infinity

Domain-domain interaction results in magnetic domains separated by **magnetic domain walls**



$M=0$

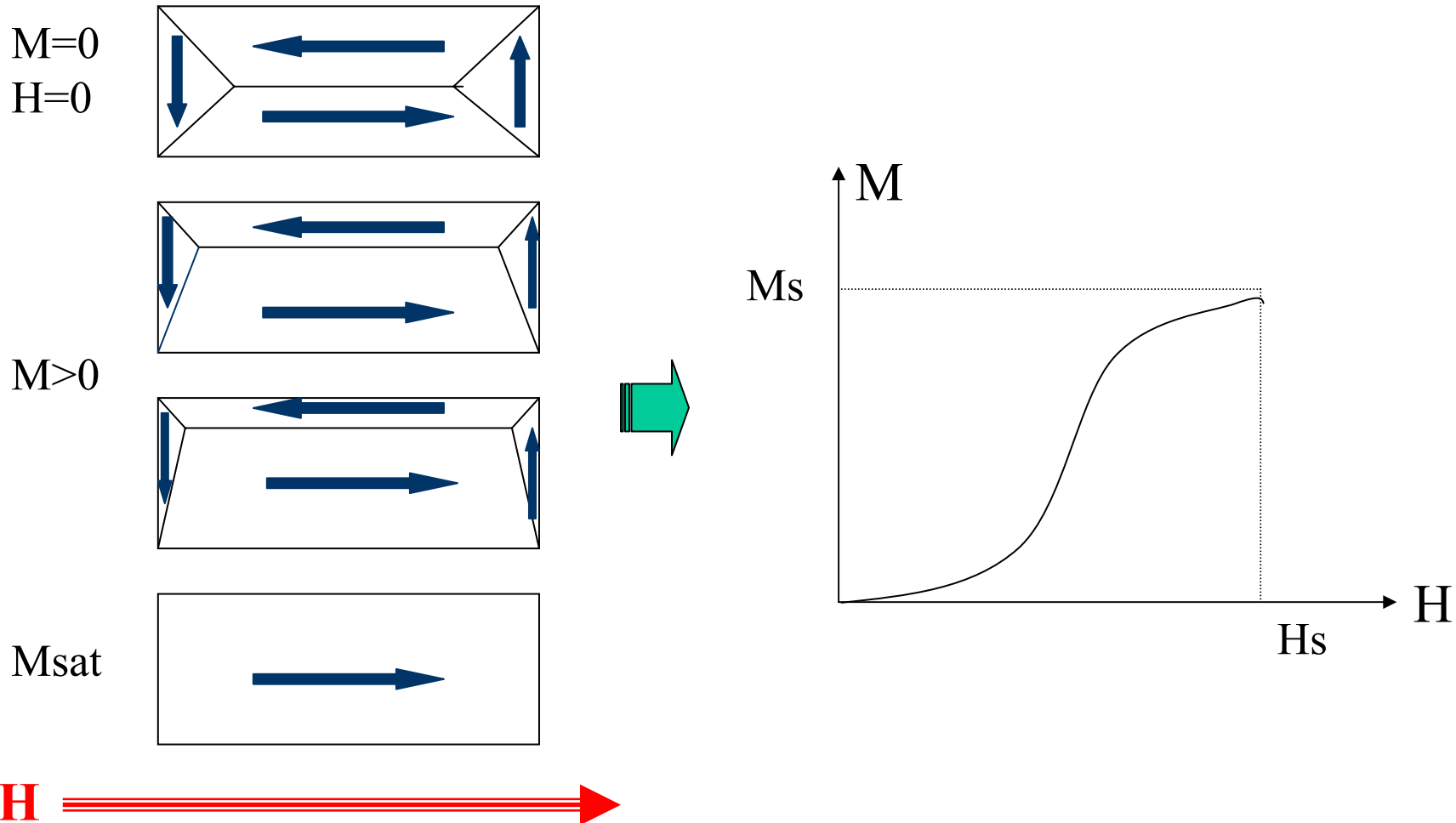
Orientation of dipoles in domain walls changes gradually



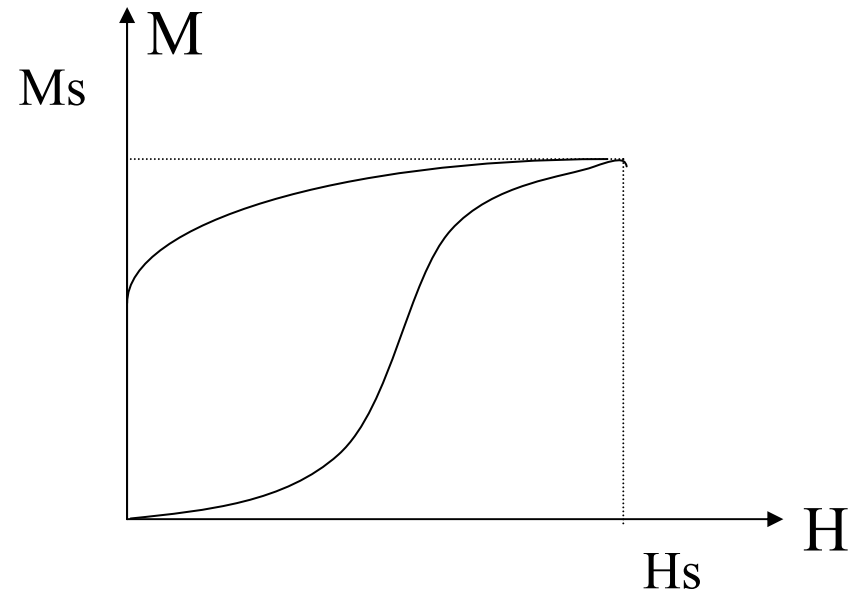
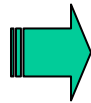
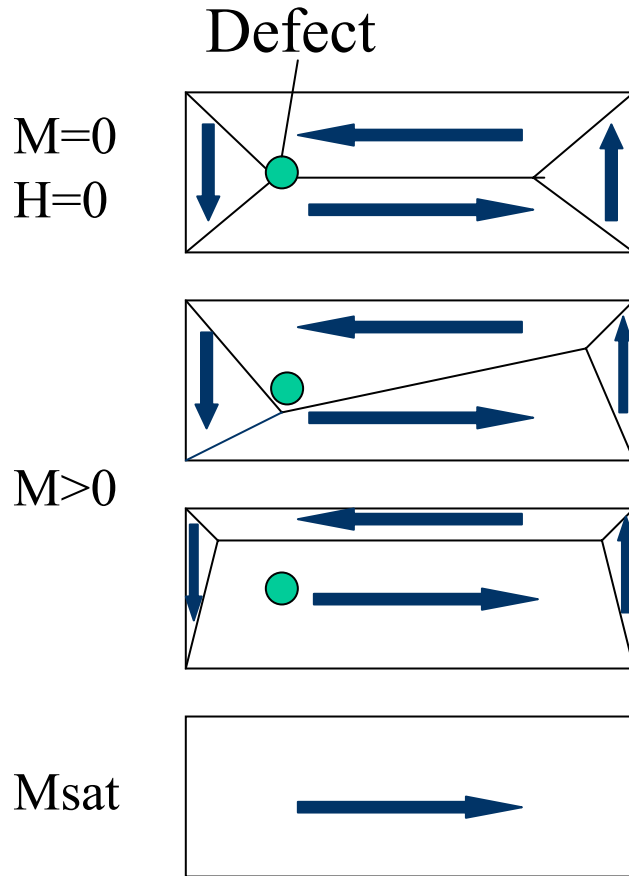
The Basic Mechanisms of Magnetization Process

- Domain wall motion:
 - Reversible
 - Irreversible
- Domain rotation:
 - Barkhausen jumps: irreversible effect
 - Small angle rotation: reversible effect

Reversible Magnetic Domain Motion

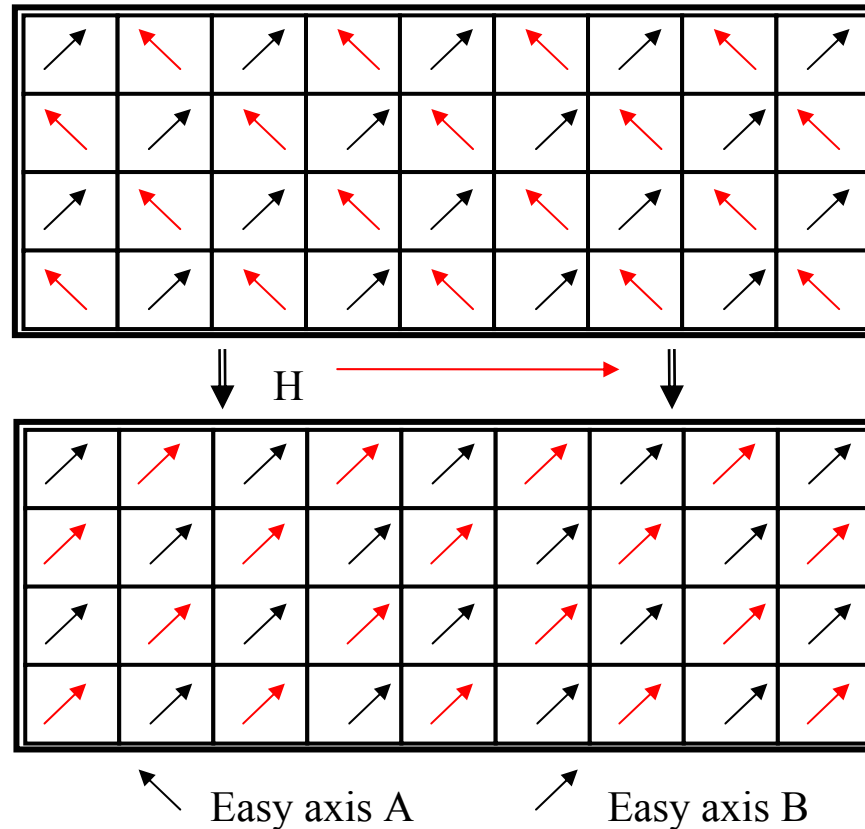


Irreversible Magnetic Domain Motion

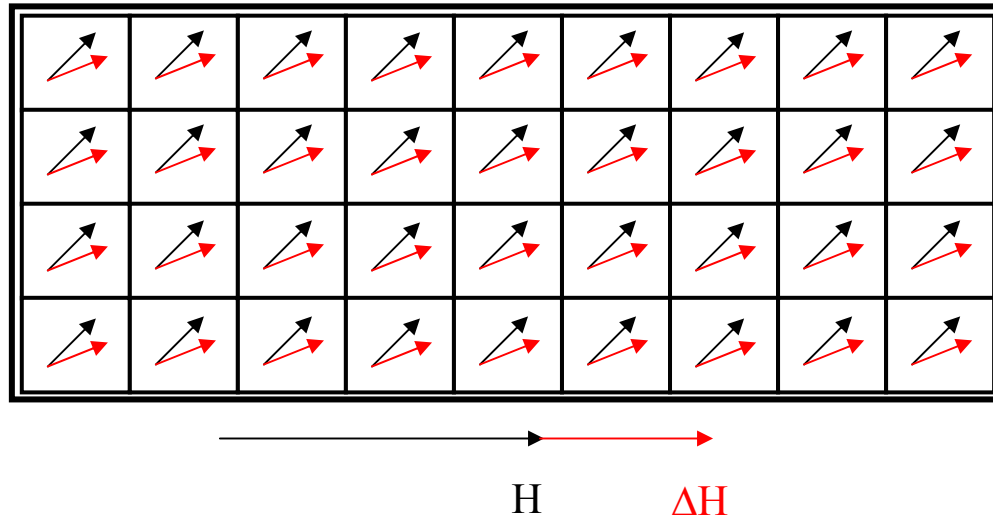


H

Irreversible domain rotation: Barkhausen Jumps



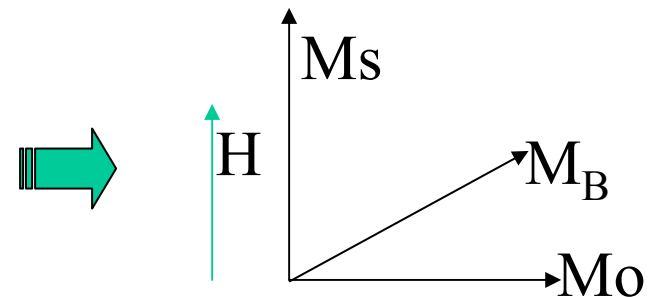
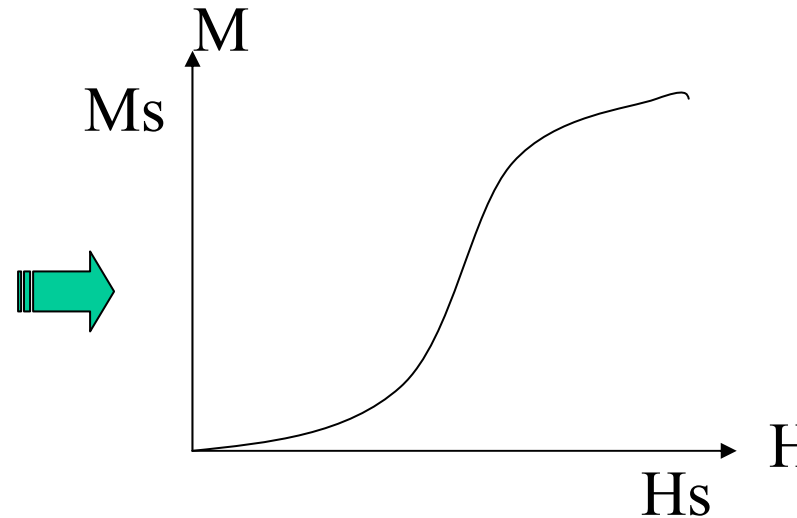
Reversible Rotation of Domains



Reversible magnetic domain rotation after
the irreversible magnetisation process

The Magnetization Process

- Virgin curve
 - Intrinsic magnetization changes under external field
 - Main curve: three parts
 - Domain wall motion
 - Barkhausen jumps
 - Rotation of magnetization
 - Minor loops
- Saturation M_s
 - Completely oriented dipoles

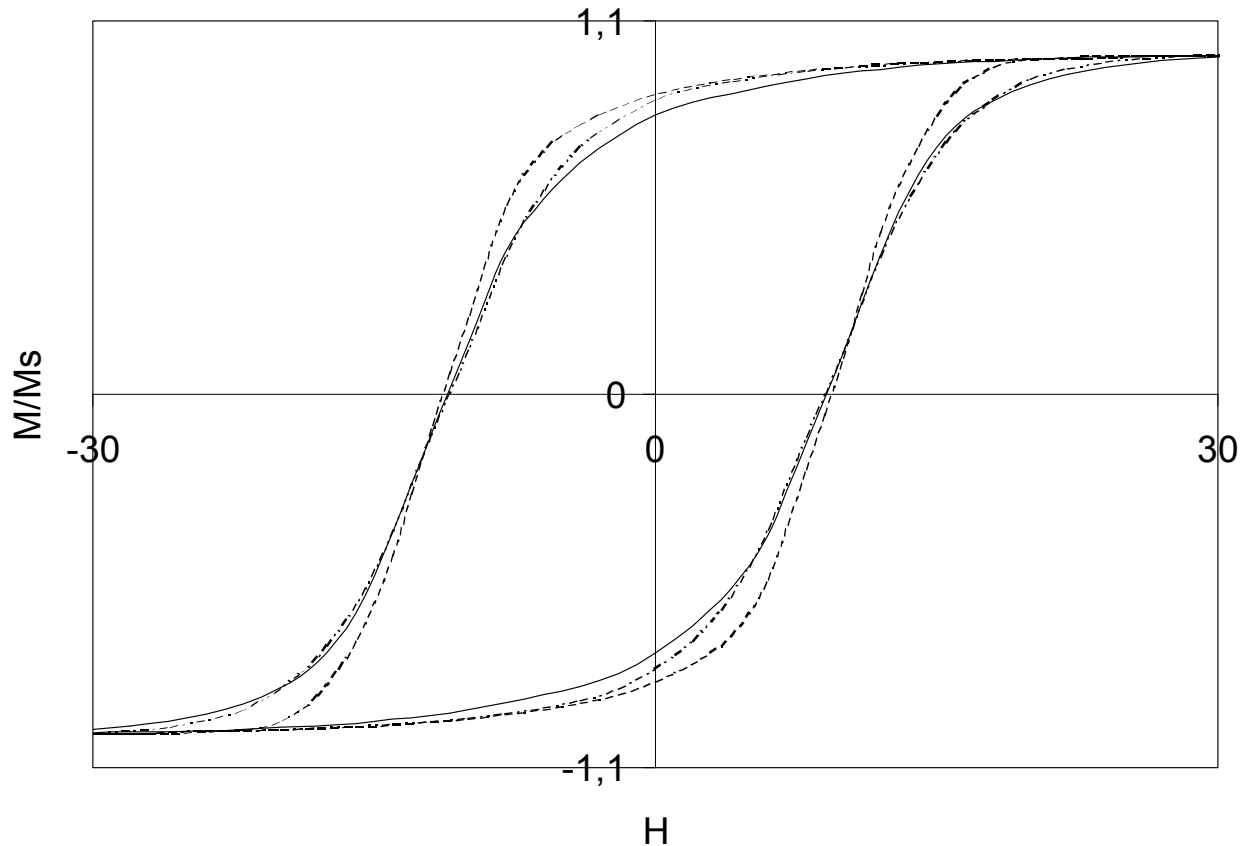


The Magnetization Process

- B-H loop
 - Saturation & back
 - Irreversible process – remanence
 - Coercive force (field) & coercive slope
 - Properties & dynamic properties: f , T , σ
 - Single phase systems have symmetric B-H loops
 - Minor loops: Inside the B-H loop
 - Size of B-H loops: hard - soft - semi
 - Non-single-phase materials may result in asymmetric B-H loop
 - Large Barkhausen Effect: an interesting property

B-H loop

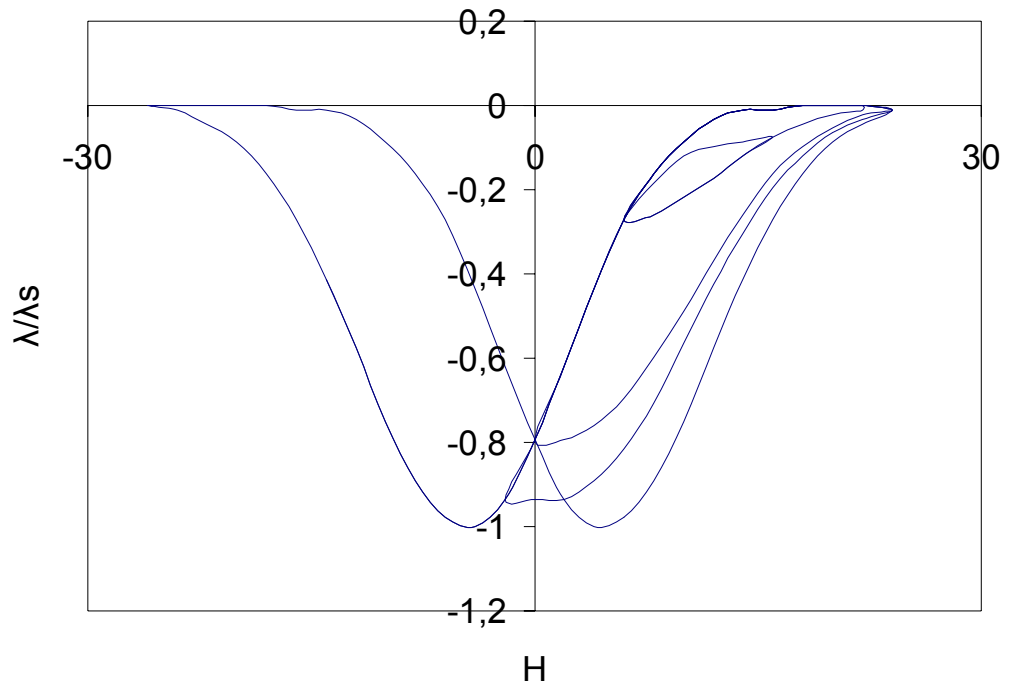
Main parameters: Temperature - Stress - Frequency



Magnetic effects

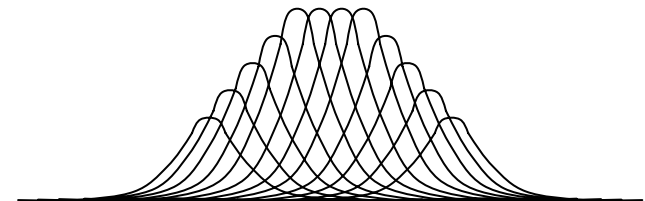
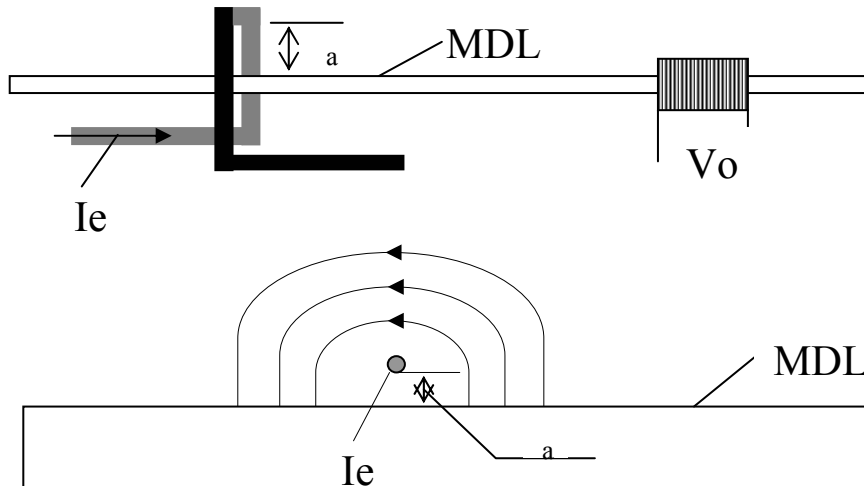
Magnetostriction:

- Magnetic domain rotation (reversible and irreversible)
- $\pm\lambda(H)$: zero, classic, unhysteretic, giant, colossal
- Dynamic properties, hysteresis



Magnetic effects

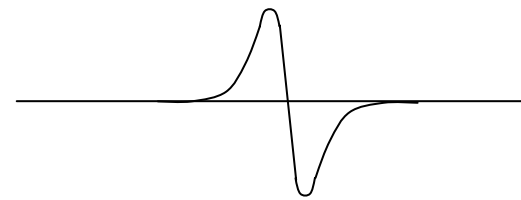
Magnetostrictive Delay Lines: an application of the magnetostriction effect



Generated microstrains



Propagating elastic pulse

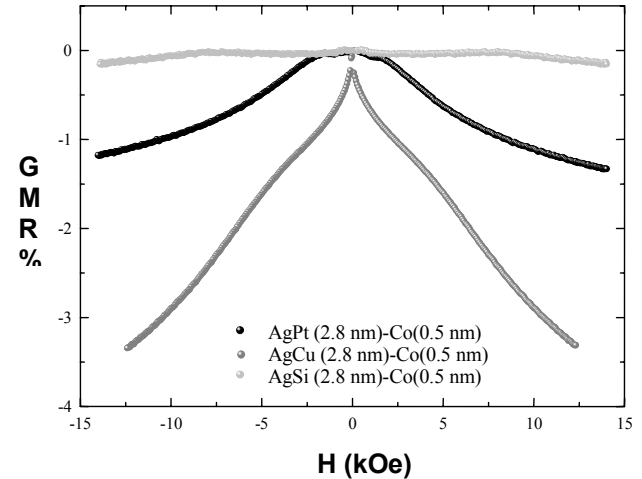


Detectable change of flux density

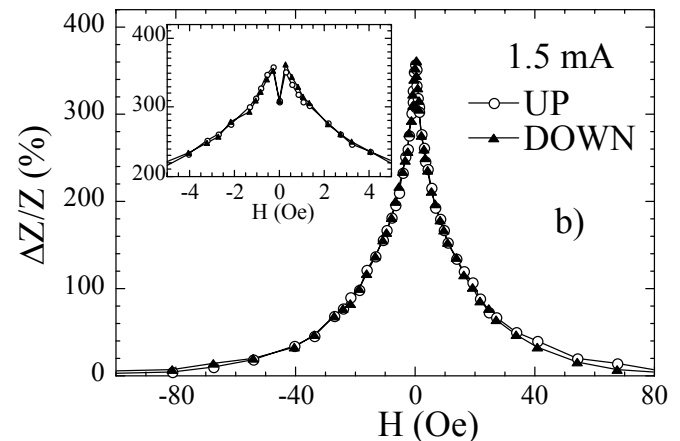
Magnetic effects

Z-H loops

Magnetoresistance
(MR, AMR, GMR, CMR)



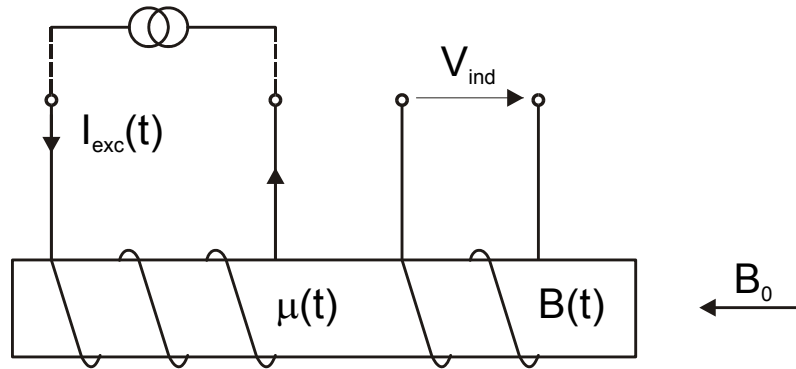
Magnetoimpedance
(MI, SI, GMI)



Magnetic effects

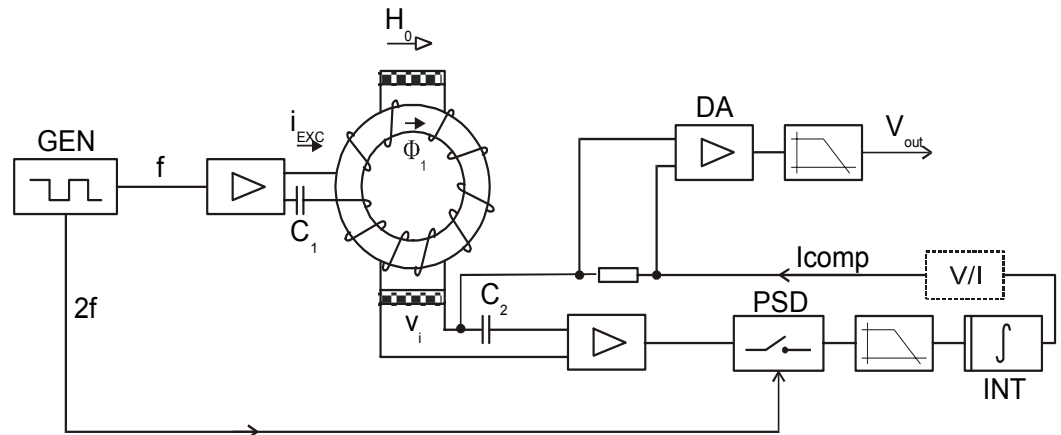
Inductive effects

Wiedeman effect



Domain wall nucleation
& propagation

Classic set-ups
(LVDT, fluxgates)



Magnetic effects

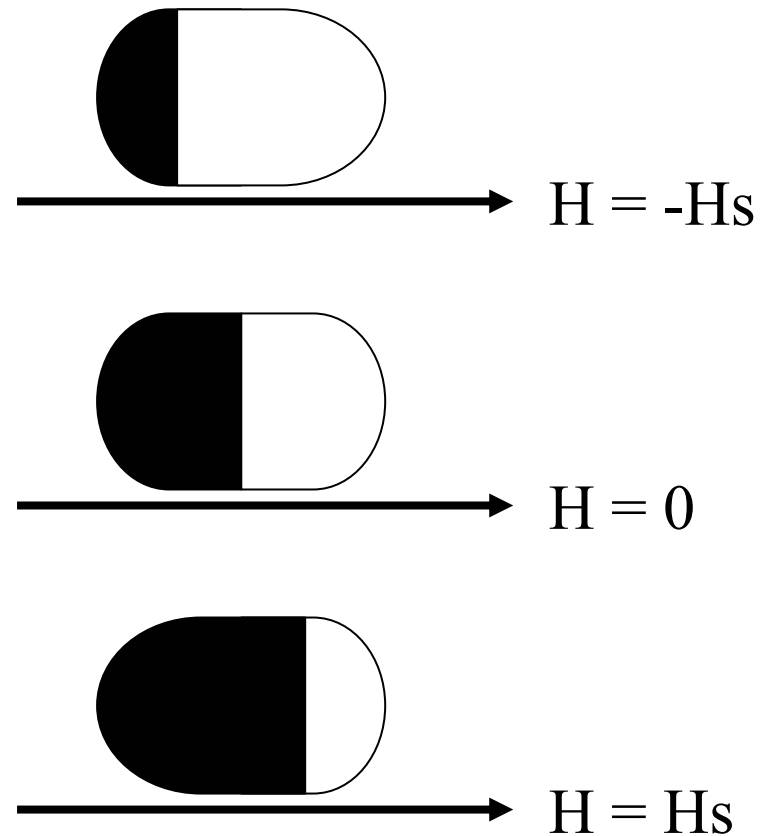
Magneto-optic effects

Bitter, Kerr, Faraday effects

Use of M-O effects

Case study:

displacement sensor

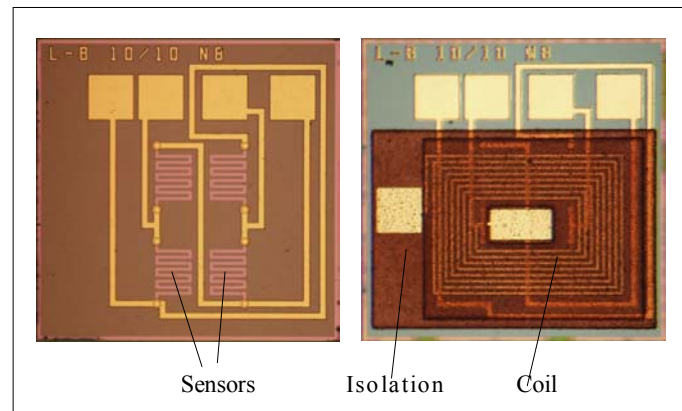
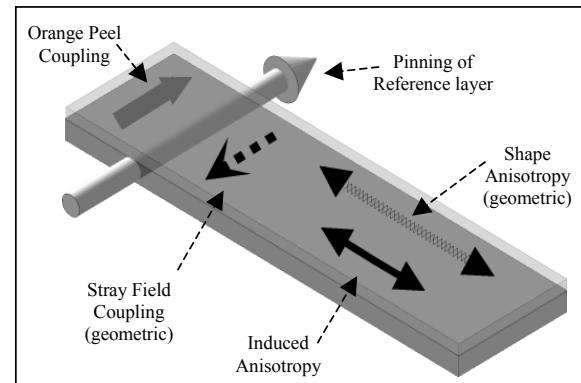


Magnetic effects

Spintronics

Spin valves

Spin tunneling



Magnetic materials

(Fe Co Ni)-(ETM)-(RE)-(NMM)

Bulk

Stress relief

Thin films

Inducing anisotropy

RQ (ribbons & wires)

Tailoring B - λ - $Z(H)$

Particulate media

Nanocrystallization

Composites

Micromechanics



Applications of magnetic materials

Applications of magnetic materials

Power

transformers

motors

actuators

Recording

recording media

recording heads

technology

&

Sensors

Magnetic Sensors: An Overview

Part B: Sensors

Sensors

- Position

- Position (tapes, digitizers, 3-d)
- Dilatometry: LVDT, MDL
- Speed & vibration: acceleration, ...

- Stress

- Load cells & torque meters
- Pressure gauges and stress sensors
- Force/pressure digitizers

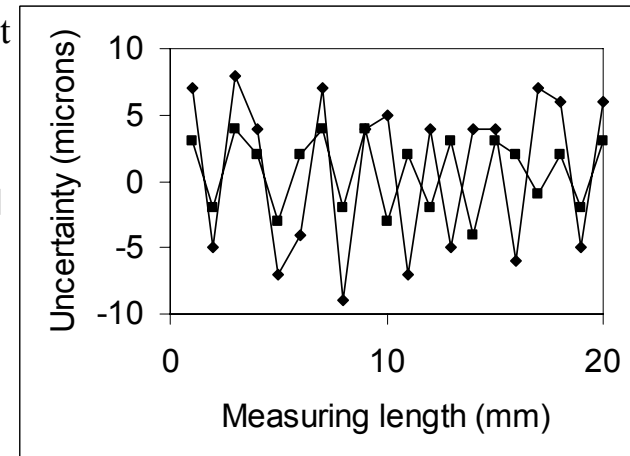
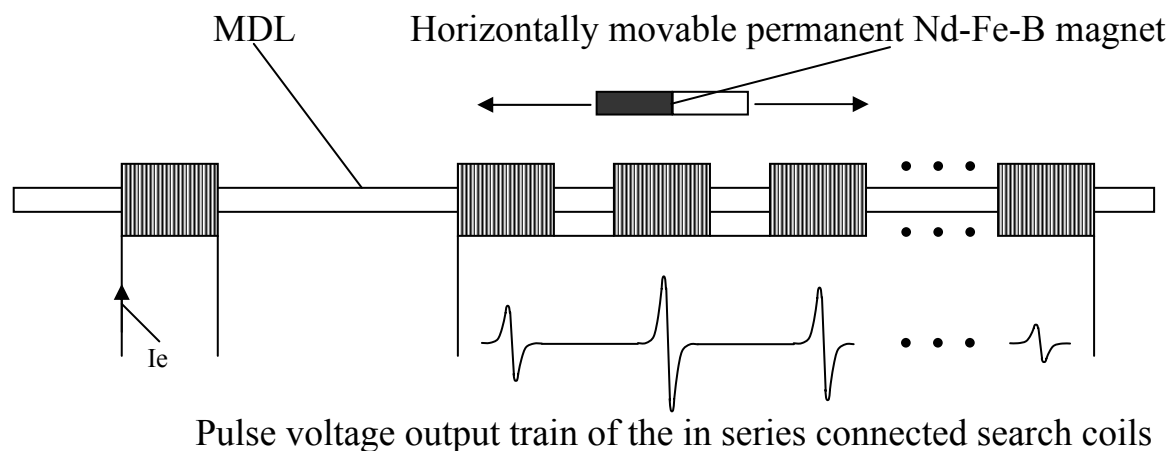
- Field

- NDT applications
- Recording
- Compass

Data from EMSA 2002, Athens, Greece

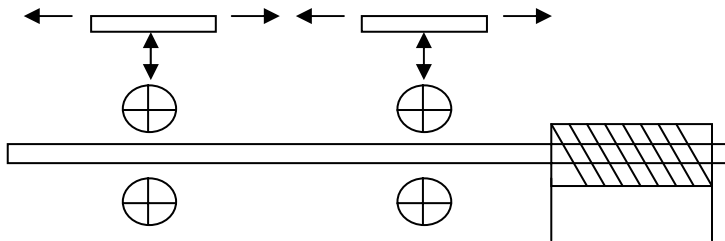
Position Sensors

- **Position sensor based on the magnetostrictive delay line technique**
 - Sensitivity: 5 μm ; Uncertainty: $\pm 10 \mu\text{m}$
 - Drawbacks: ambient field sensitive
 - Characteristics are optimised by using amorphous alloys

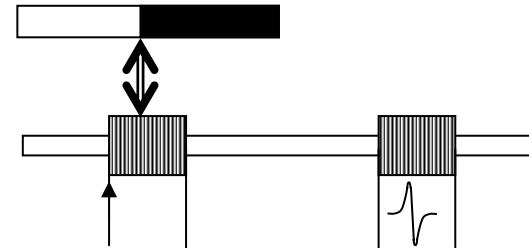


Position Sensors

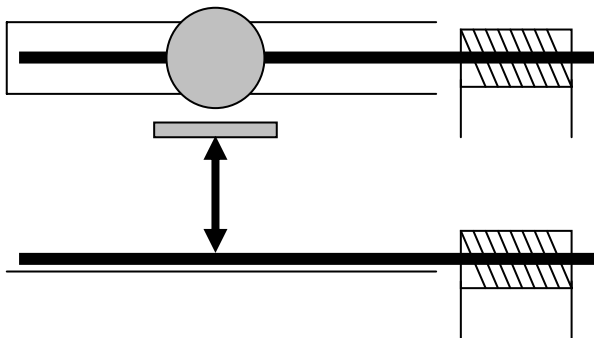
(MDL technique cont.)



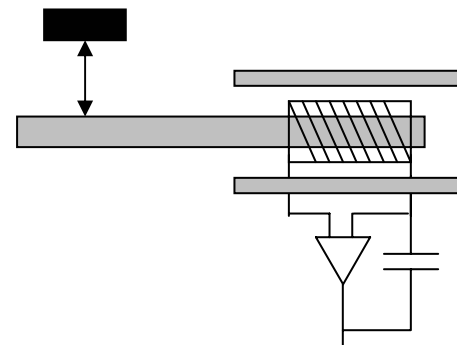
Dilatometer and stress sensor



Moving magnet sensor



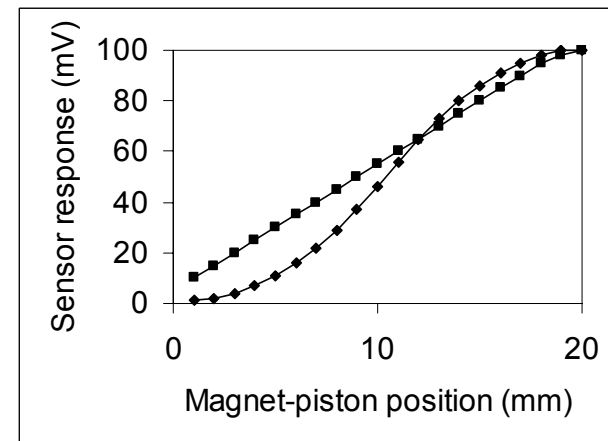
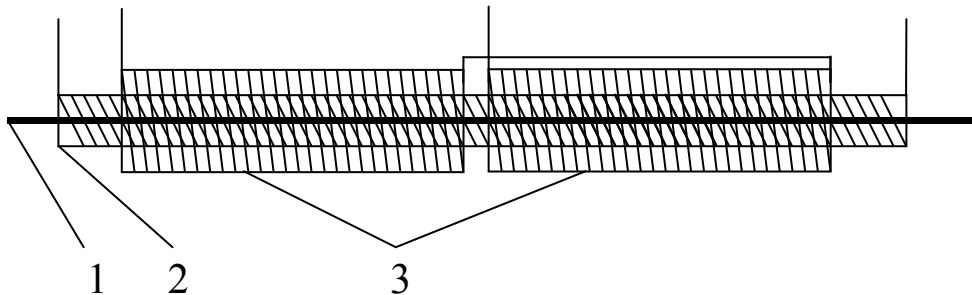
ECT-MDL digitizer



ECT-MDL digitizer

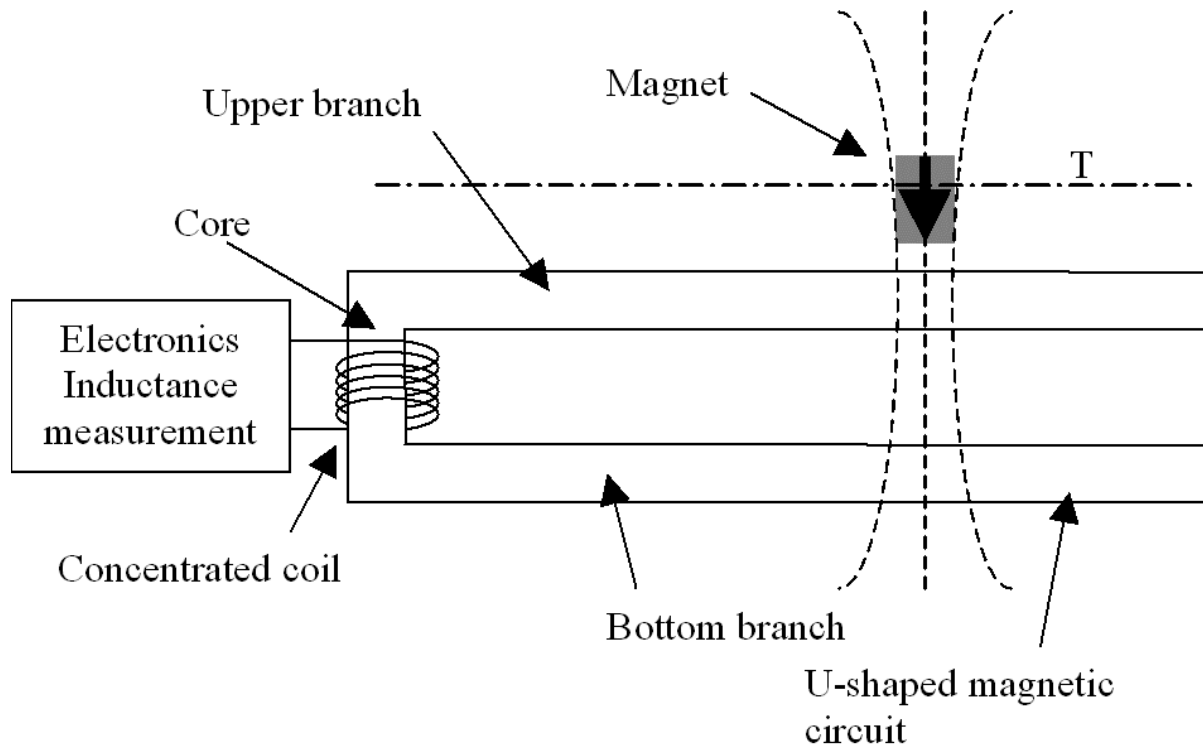
Position Sensors

- Position sensor based on the linear variable differential transformer (LVDT) set-up. (1) Soft magnetic material, (2) Excitation coil, (3) In series opposition search coils.
 - Sensitivity: 100 μm
 - Uncertainty: $\pm 500 \mu\text{m}$
 - Repeatable response from -70 C to 150 C
 - Drawbacks: ambient field sensitive
 - Improved characteristics by material tailoring



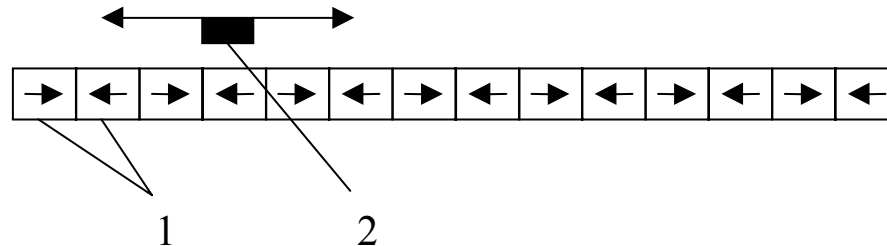
Position Sensors

Position sensor based on an inductive principle



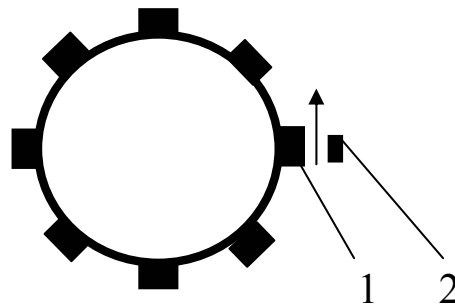
Position Sensors

- Position sensor based on permanent magnet tape. (1) Permanent magnetic thin films, (2) Searching magnetic head.
 - Sensitivity: 100 μm
 - Uncertainty: $\pm 500 \mu\text{m}$
 - Repeatable response from -70 C to 150 C
 - Drawbacks: ambient field sensitive
 - Characteristics can be improved by material tailoring



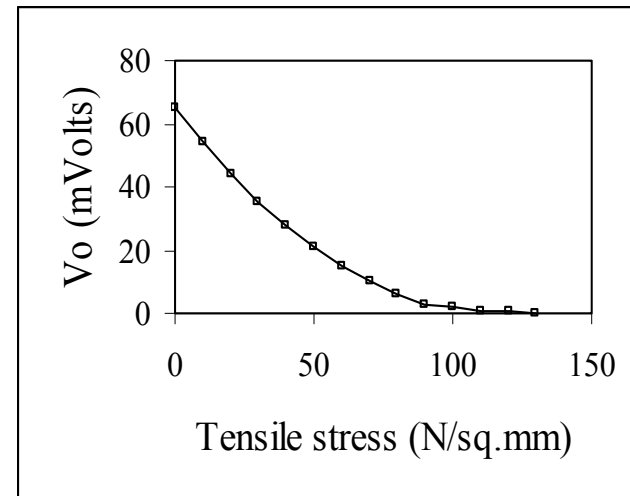
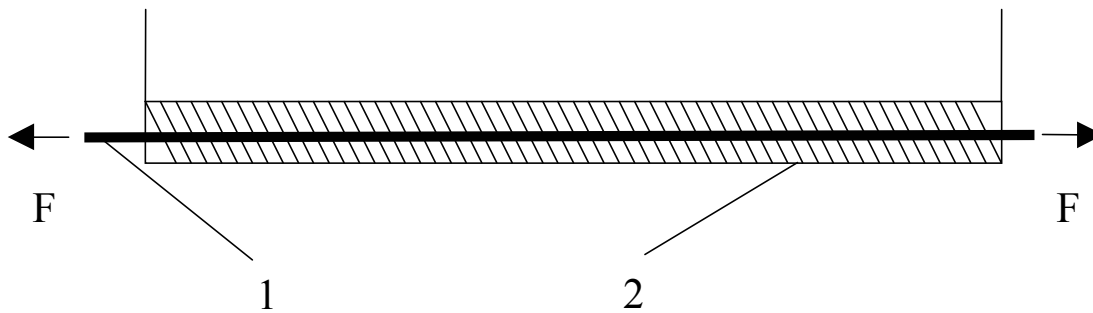
Position Sensors

- Angular positioning sensor. (1) Radial permanent magnets in tooth arrangement, (2) Searching field sensor.
 - Repeatable response from -70 C to 150 C
 - Great reproducibility allowed use in automobile industry (ABS)
 - Drawbacks: ambient field sensitive
 - Advantages: no dust sensitive



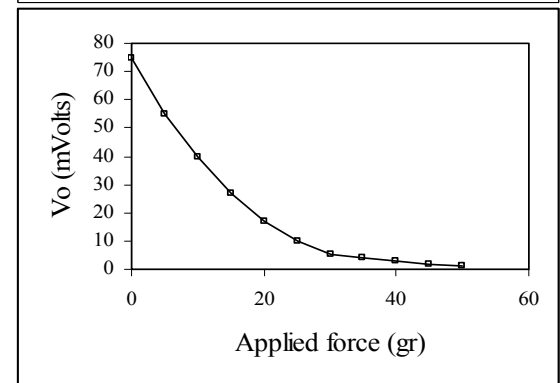
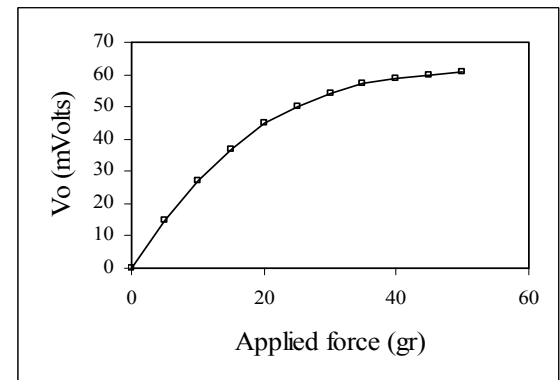
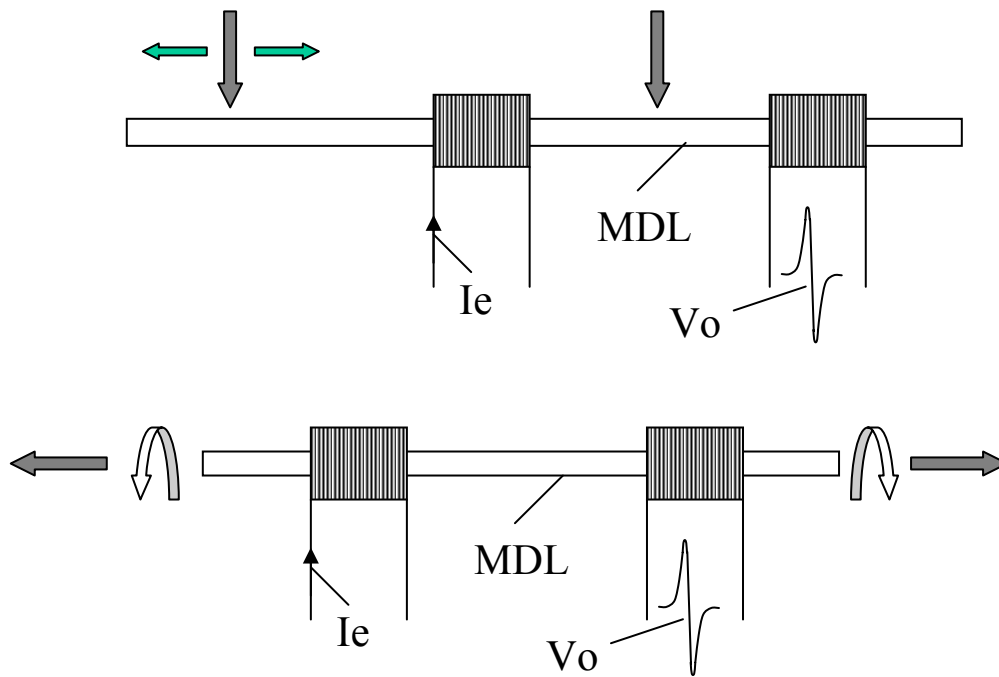
Stress sensors

- Stress sensors based on inductive effects. (1) Soft magnetic element, (2) Inductive excitation coil.
 - More sensitive than strain gauges, if amorphous alloys are used
 - Good noise level after heat annealing
 - Good reproducibility after field annealing
 - Ambient field sensitive



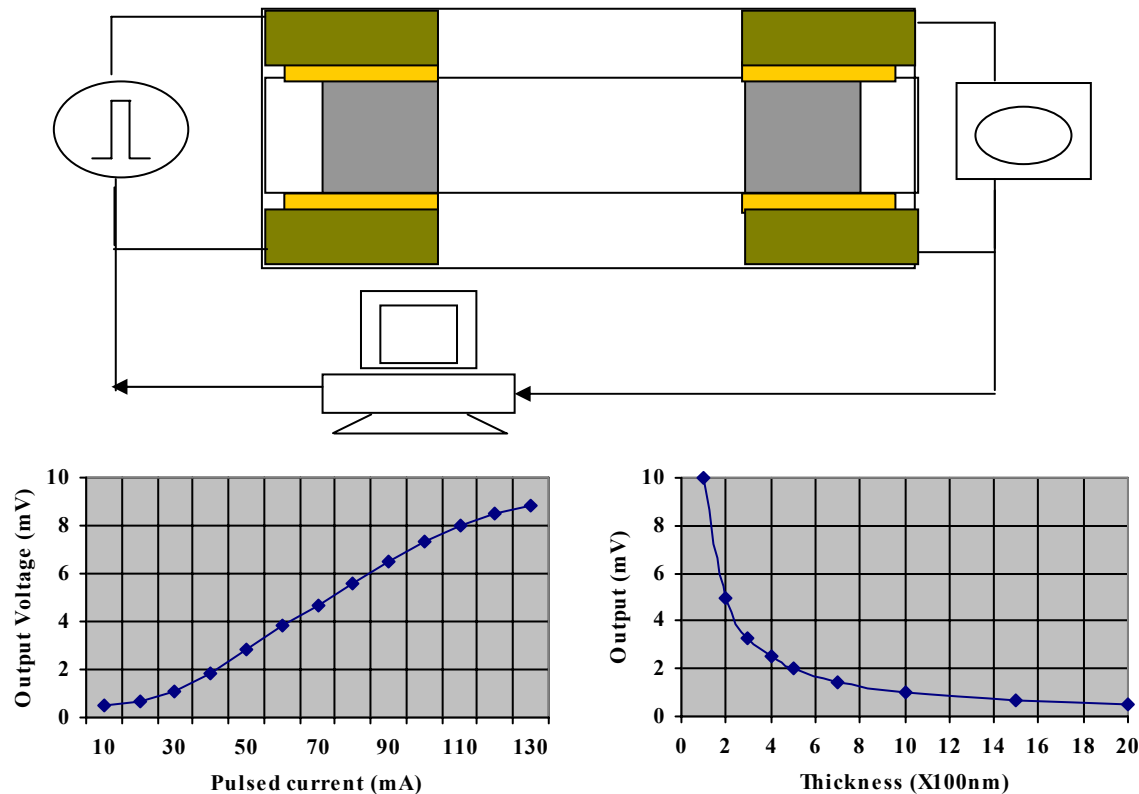
Stress sensors

Pressure, stress & torque sensors based on MDLs



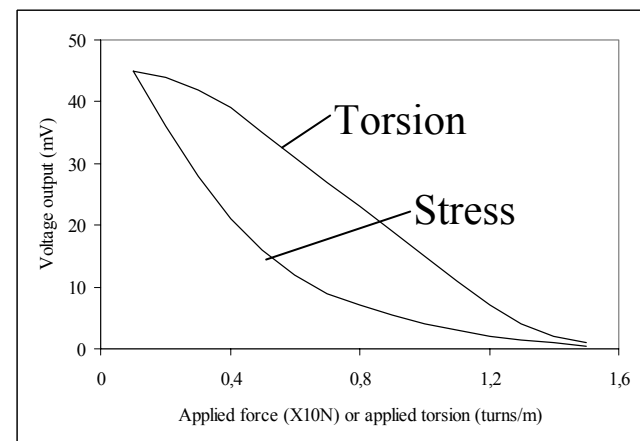
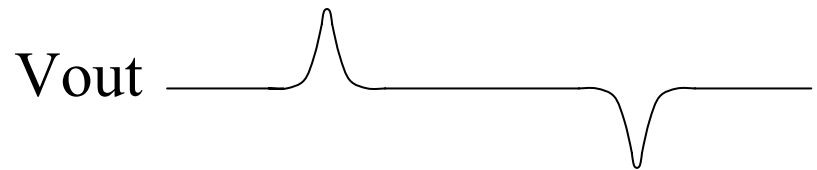
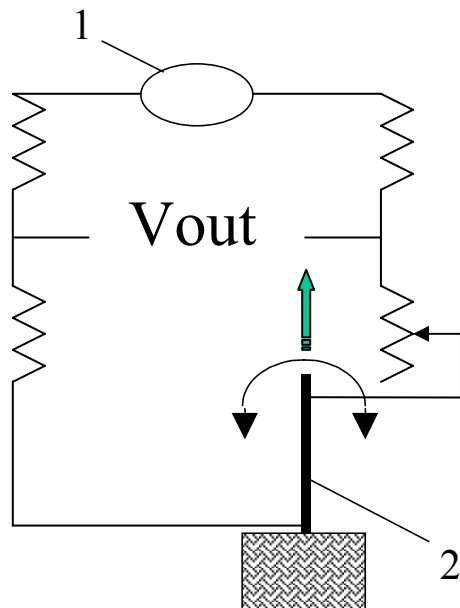
Stress Sensors

Thickness sensor based on a coilless MDL set-up

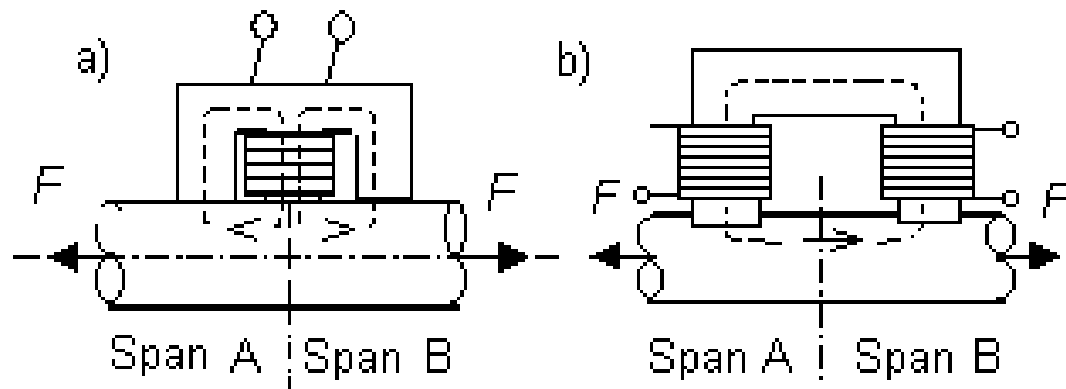
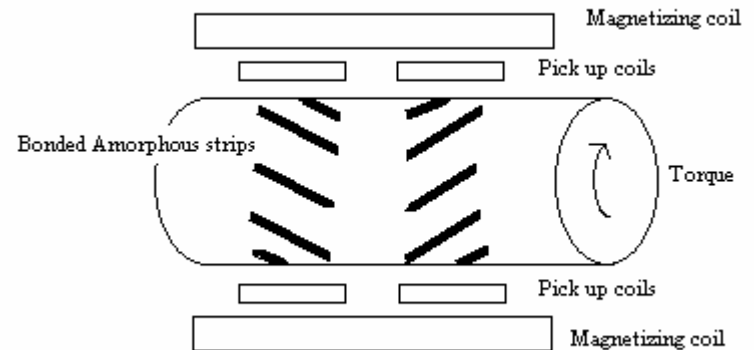
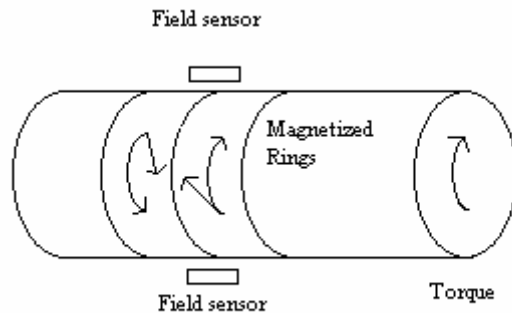


Stress Sensors

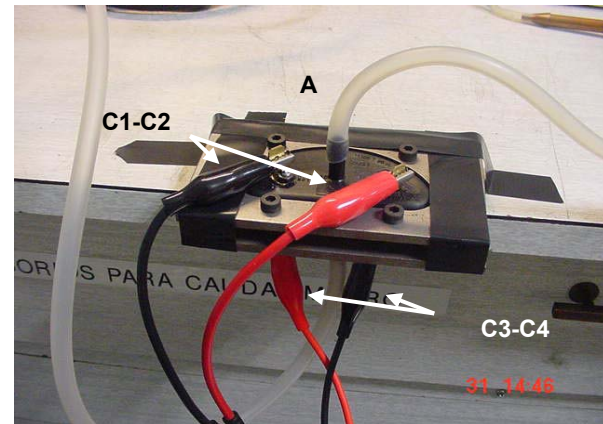
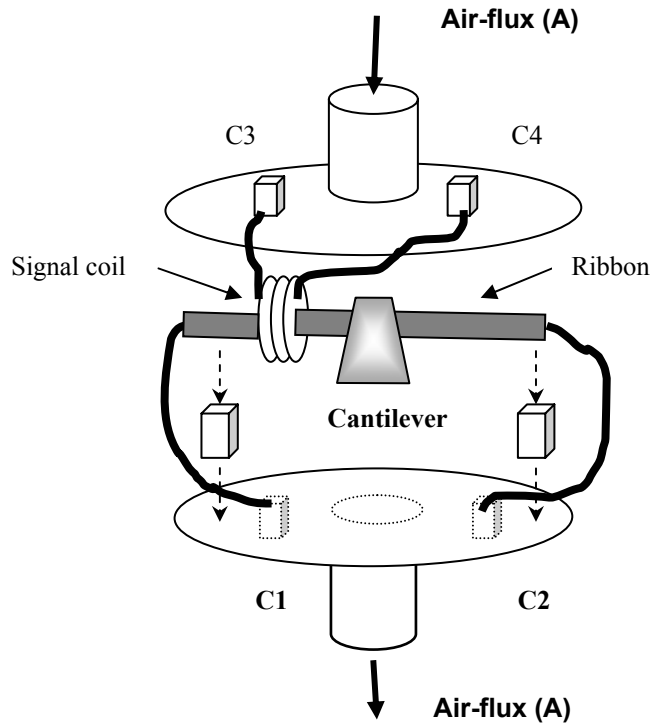
- Magneto-inductive (MI) stress & torque sensors. (1) Sinusoidal excitation circuit, (2) MI element.
 - Very sensitive, especially in high frequencies



Stress Sensors: Torque Meters



Air-flux Sensors Based on the Inverse Wiedeman Effect

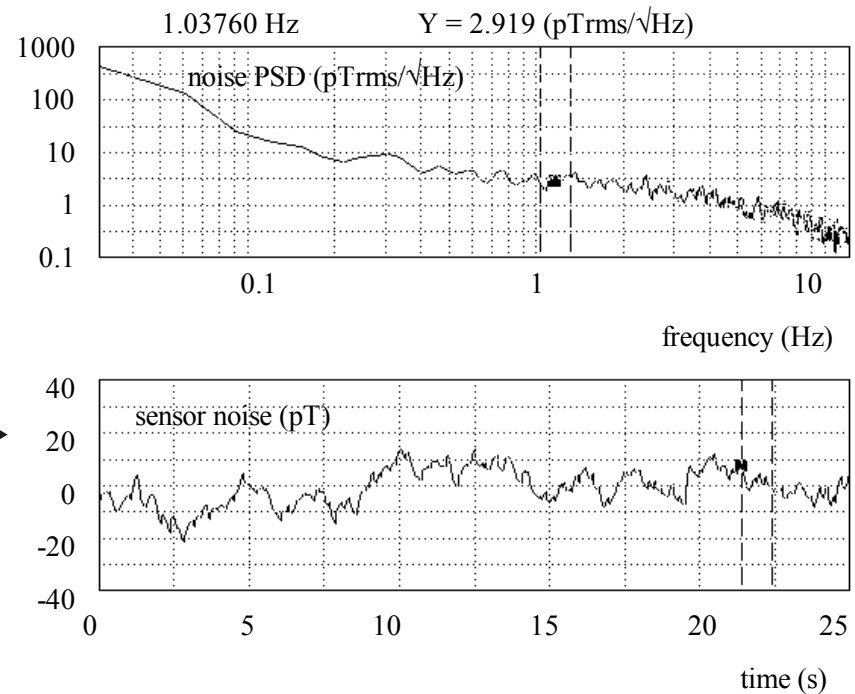
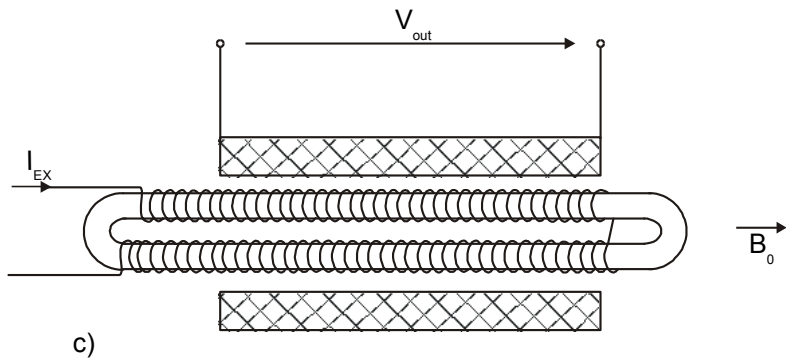


Ambient field dependence

- A serious drawback in mechanical sensors based on magnetics
- There are three solutions:
 - Two axes shielding by nanocrystalline thin ribbons
 - Active compensation by induced field in some cases (MDL and MI set-ups)
 - Smart field sensing

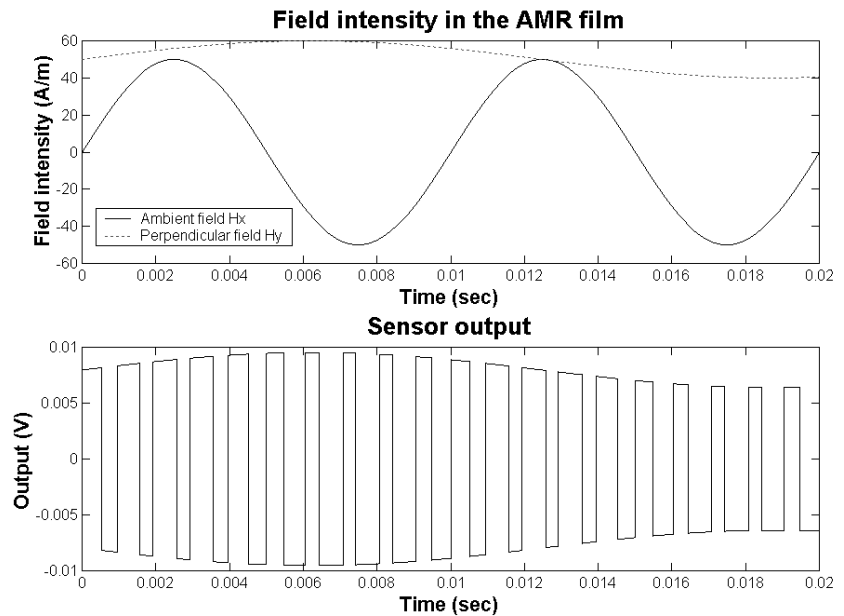
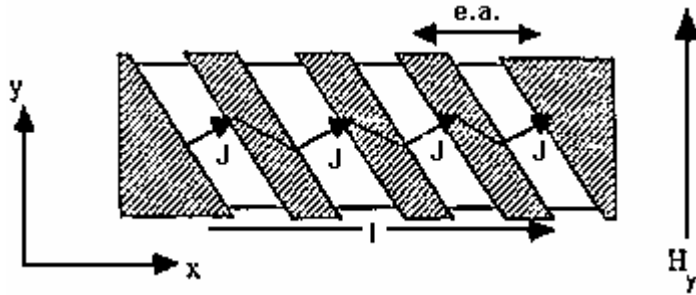
Field Sensors

Fluxgates



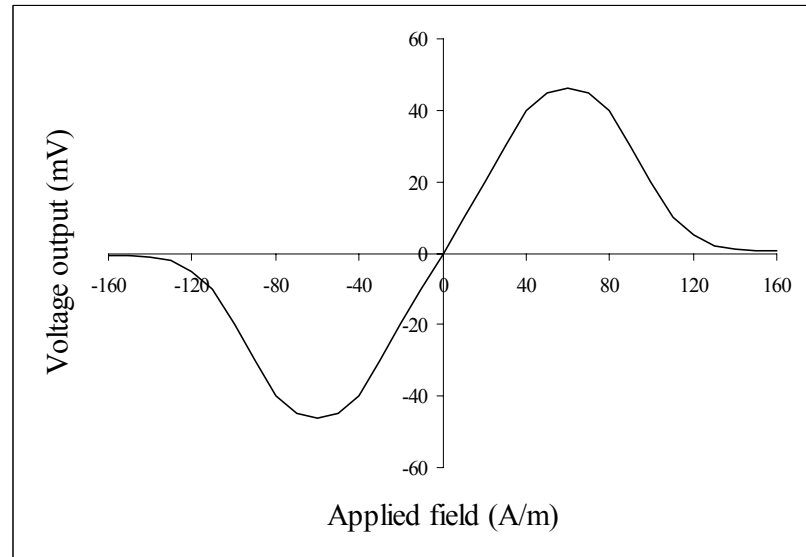
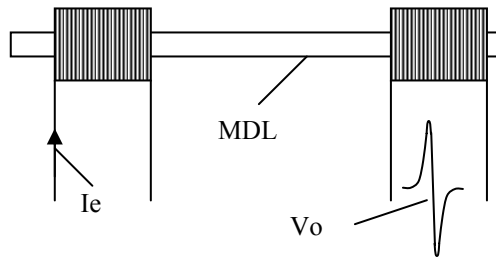
Field Sensors

Magnetoresistive heads



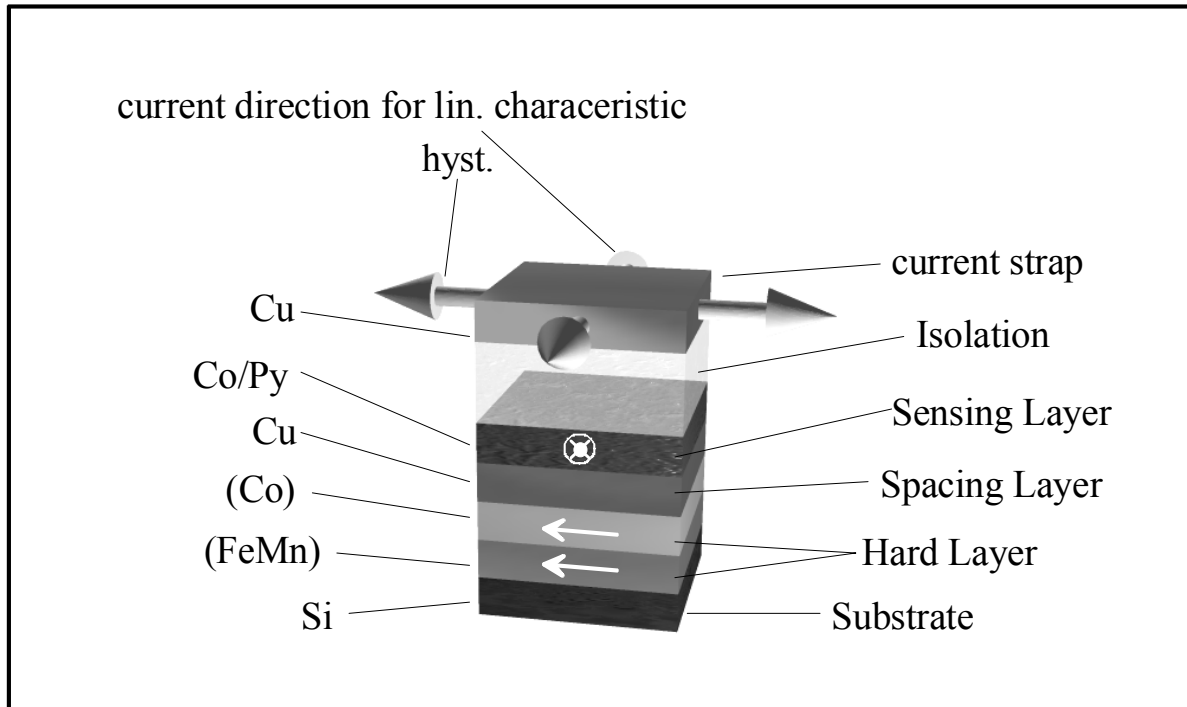
Field Sensors

MDLs



Field Sensors

GMR & Spintronics

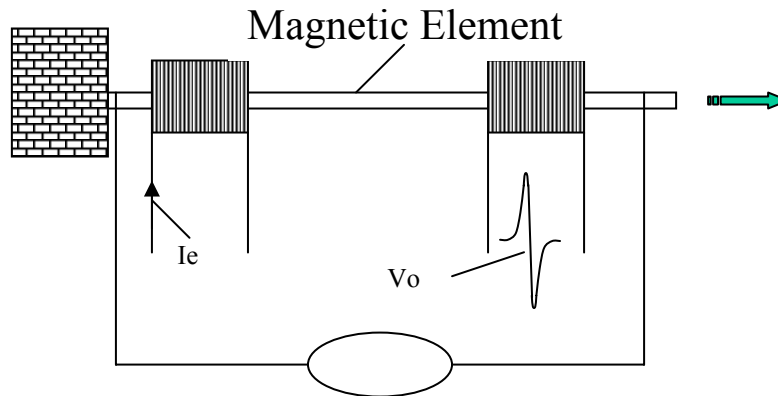


Smart Sensors

Multifunctional system: combination of measurements

- - Magnetostrictive delay line
- - Magnetoimpedance set-up
- - Domain wall nucleation and propagation set-up

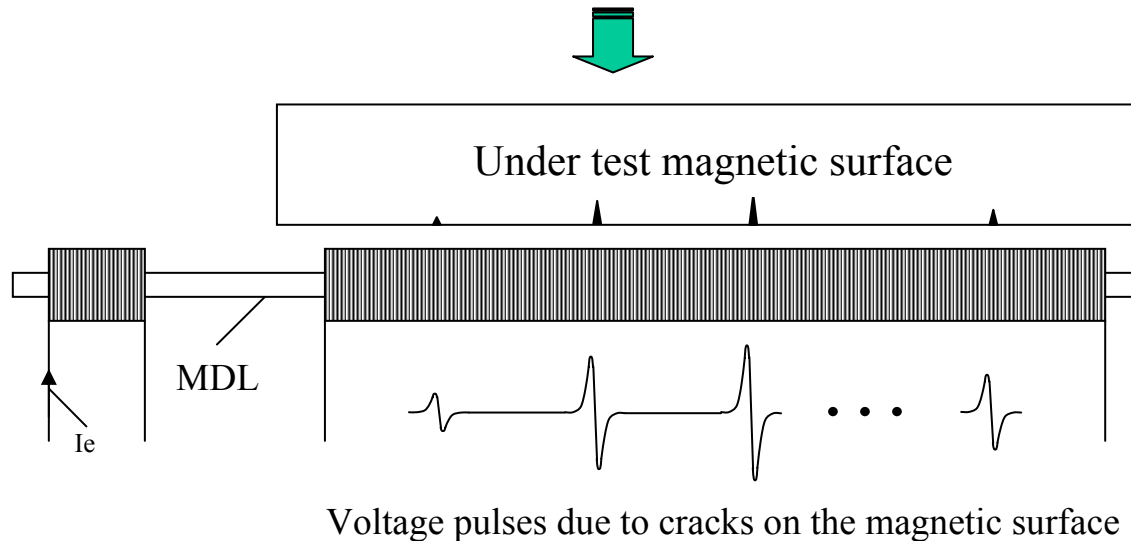
Using three different types of response to determine three different inputs



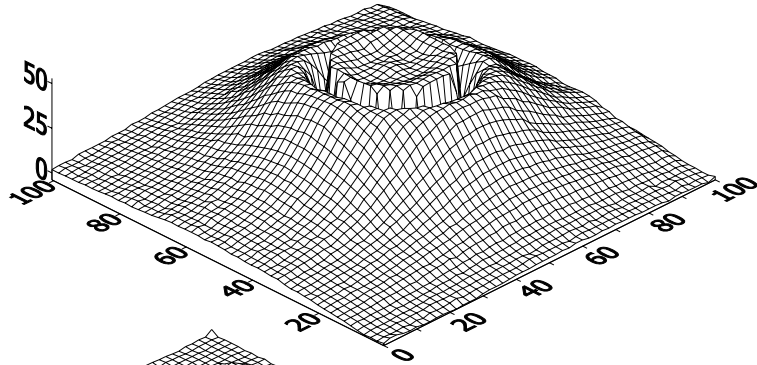
Sensor Applications

- Industrial

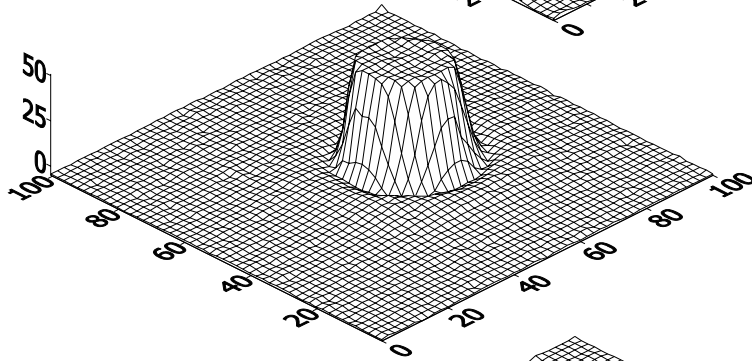
- Sensors in production (piston position, stress monitoring, else)
- Sensing systems for industry
- NDT&E using field detection techniques



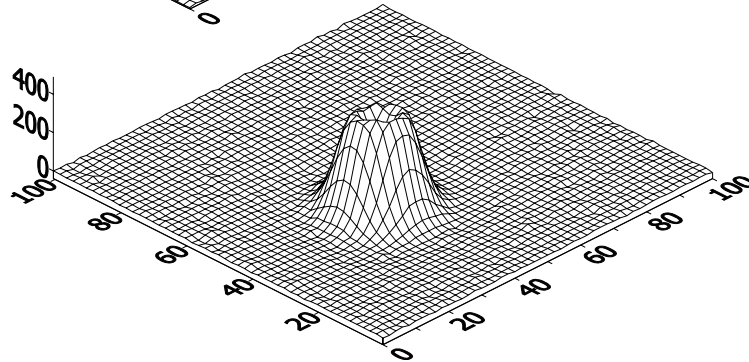
A Comparison Between Hall and GMR Sensors for NDT&E Inspection



GMR Sensor Response

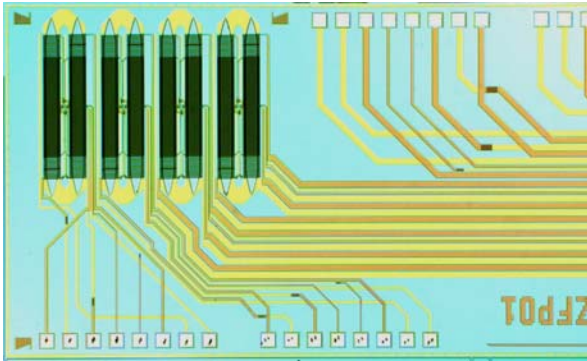


Shielded GMR Sensor Response

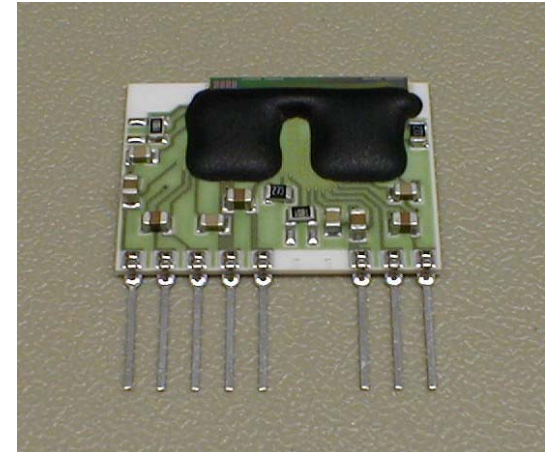


Hall Sensor Response

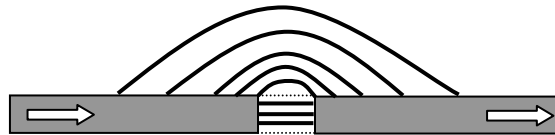
A Micro-Fluxgate Arrangement for NDT&E Inspections



The 4 m-Fluxgate Sensors



The Sensor

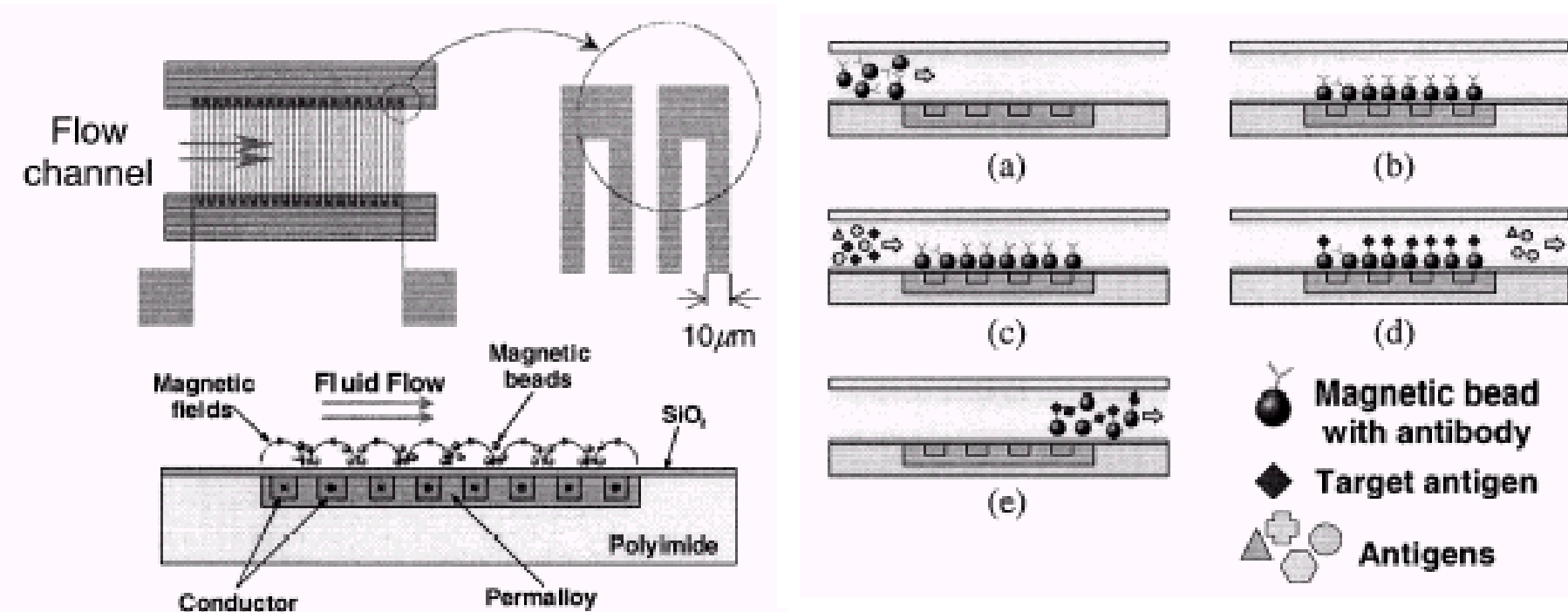


The Under Inspection Magnetic Anomaly

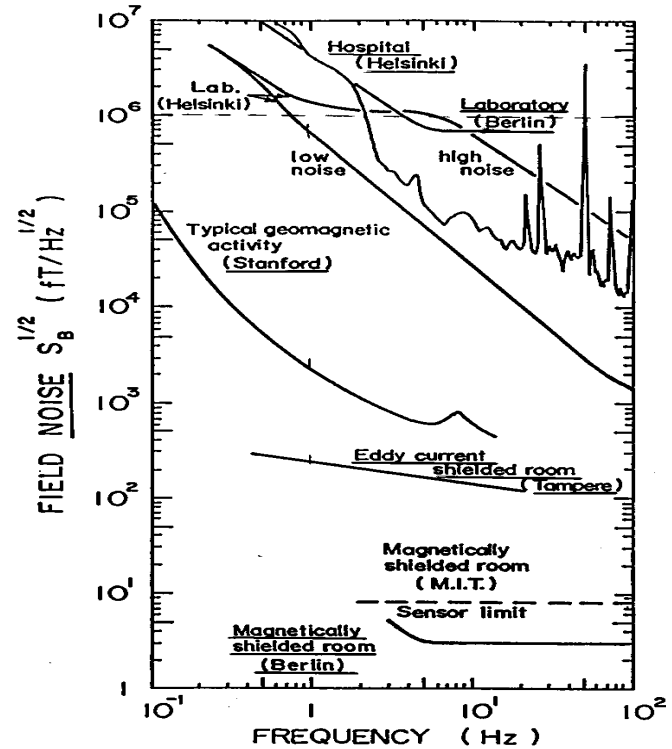
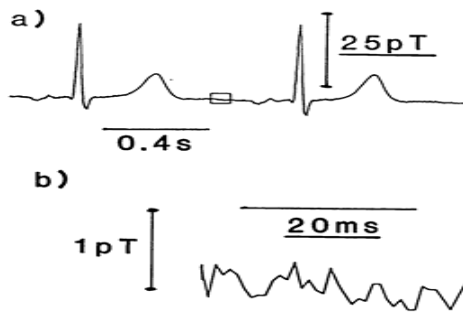
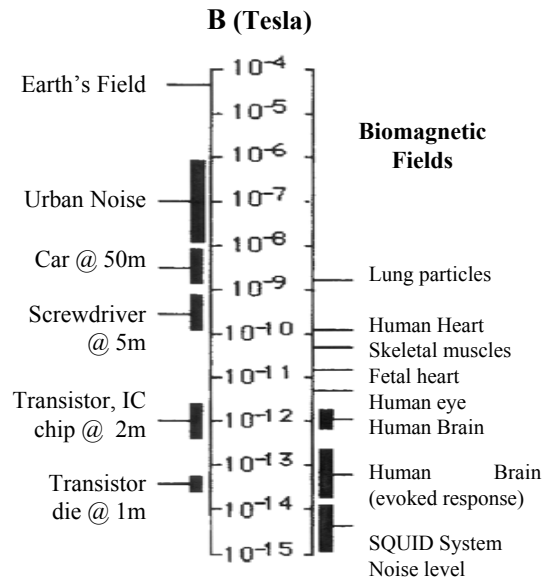
Sensor Applications

Biomedical

Field monitoring, diabetes & blood monitoring, stress & strain monitoring, cardiac measurements, artificial sphincters



Electromagnetic Measurements in Bio-Engineering

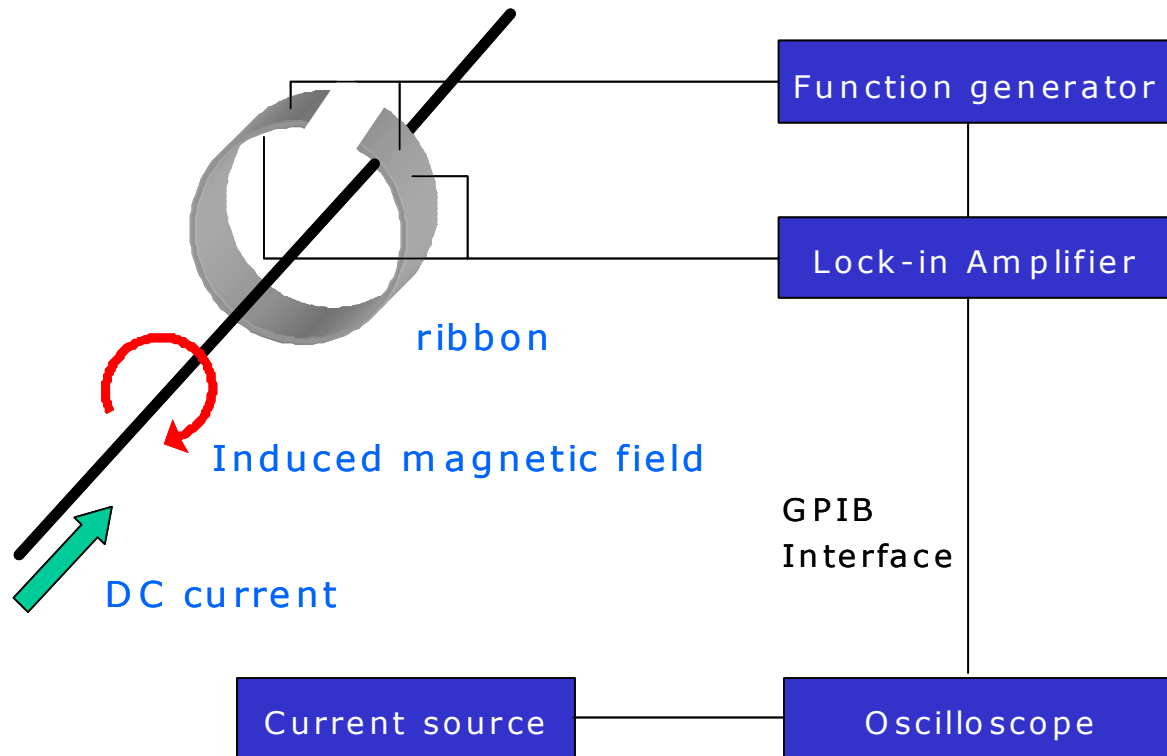


GMI Measurements

Sensor Applications

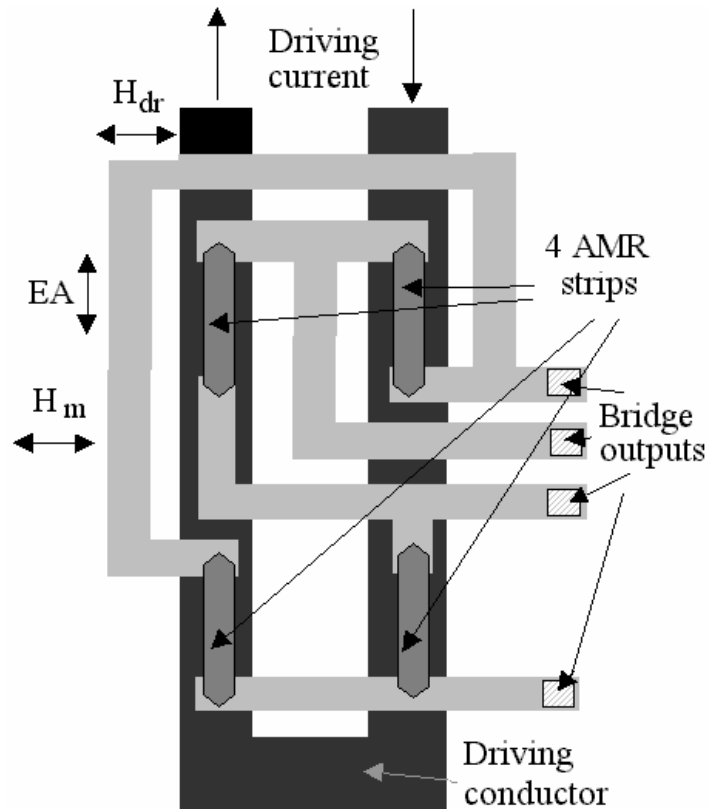
- Military applications
 - Gyroscopes (field)
 - Magnetic signatures (field)
- Automotive
 - Positioning & tracking (field)
 - Torque sensors (stress)
 - On-off- ABS rotation (positioning)
- Other applications
 - Environmental: E/M low frequency
 - Laboratory : characterization techniques
 - Domestic : current path searcher

Sensor Applications



Electric Current Meter

Micromagnetic arrangements

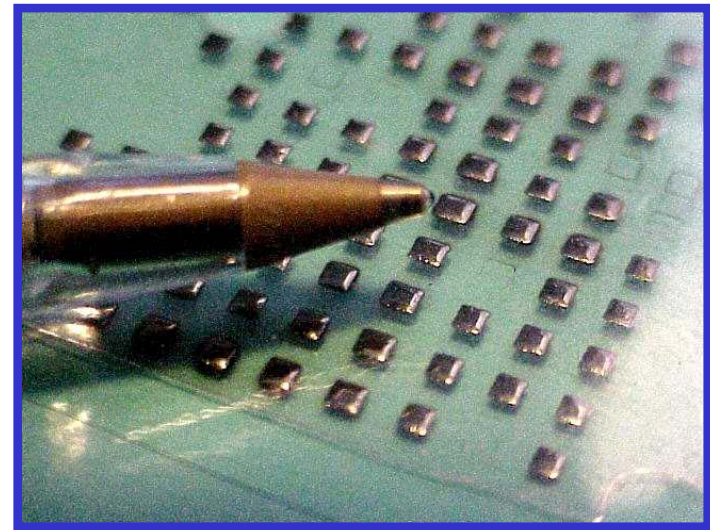
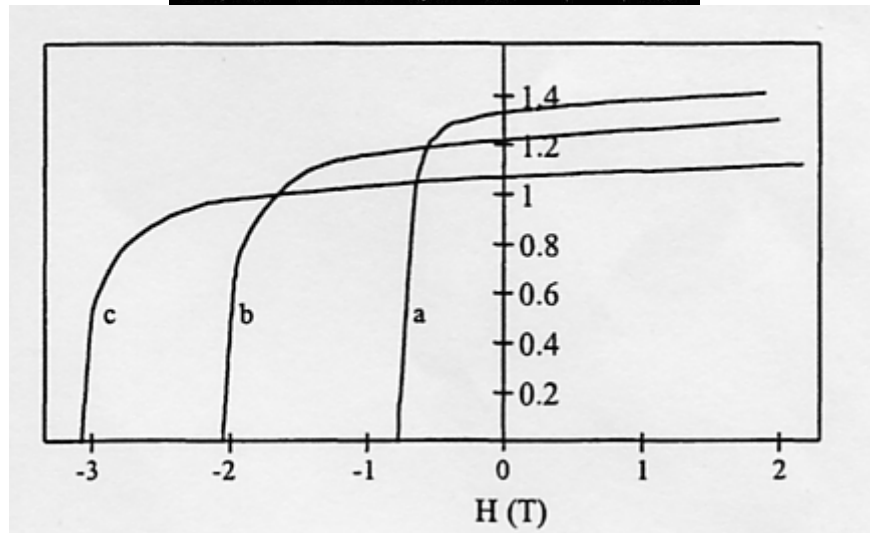
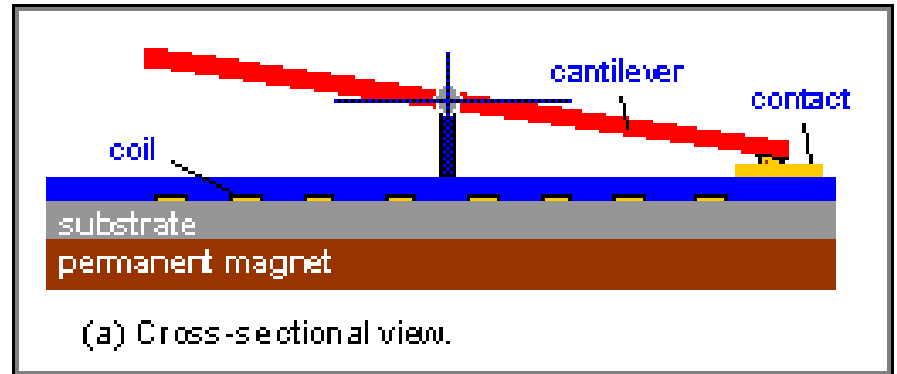
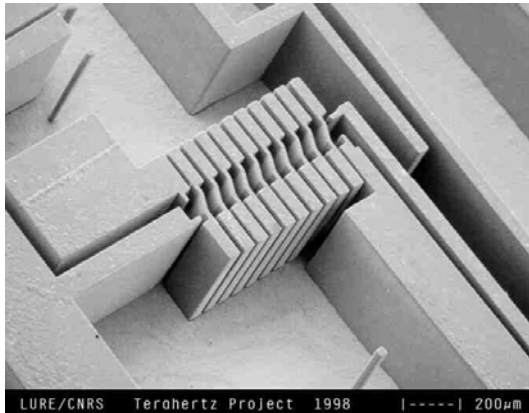


AMR Bridge



Micro-coils

Micromagnetic arrangements



Developing a sensor

- Facing-up the problem
 - measurement– range – sensitivity
 - Field of use (application)
 - Parameters affecting
- Choice of sensing principle (effect)
 - Taking into account: range – sensitivity – parameters
 - Preliminary experiments: indicative results
 - Scheduling the experiment & and the sensor

Sensor Development

- Sensing element : thin film, RQ, powder, else
- Sensing device: the first prototype
- Sensor electronics & calibration set-up
- Measurements
- Parametric effects: field, stress, temperature
- Design of the sensor housing
- Development of the sensor prototype
- Calibration & Corrective actions
- Final prototype & technical envelop

Designing the future

Is miniaturization a future challenge?

- Nanoscale resolution in writing & reading
- Sensors with secondary standard uncertainty (nanotechnology?)
- Smart multipurpose sensors
- Parametric control (field-temperature- stress)
- Silicon-chip magnetic sensors

Is there any key-parameter in designing magnetic sensors?

- Hysteresis: the key point
- Stability of B - λ - $Z(H)$
- Parametric effects: field- stress-temperature